

Why know anything about linear algebra?

Let  $f: \mathbb{R} \rightarrow \mathbb{R}$  be a differentiable

function. Then "near" the point

$a$ ,  $f$  is "almost" equal

to its tangent line

$$y = f'(a)(x-a) + f(a)$$

So  $f(x) - f(a)$  is "almost"

$$f'(a)(x-a)$$

$f'(a)$  is a  $1 \times 1$  matrix

Similarly, if  $f: \mathbb{R}^n \rightarrow \mathbb{R}^m$  is

differentiable, the total derivative of  $f$  at a point

$a \in \mathbb{R}^n$  is an  $m \times n$  matrix

$$Df_a.$$

## Concrete Applications

I) Ohm's Law, Kirchoff  
Current and Voltage Laws

$V$  = voltage

$I$  = current

$R$  = resistance

Ohm's Law:  $I = \frac{V}{R}$

## Kirchoff's Current Law

If  $I_k$  is the current flowing into node  $k$  and if there are  $n$  nodes in the circuit, then

$$\sum_{k=1}^n I_k = 0$$

## Kirchoff's Voltage Law

If  $V_k$  is the electric potential difference between two nodes and there are  $m$  connections in the circuit,

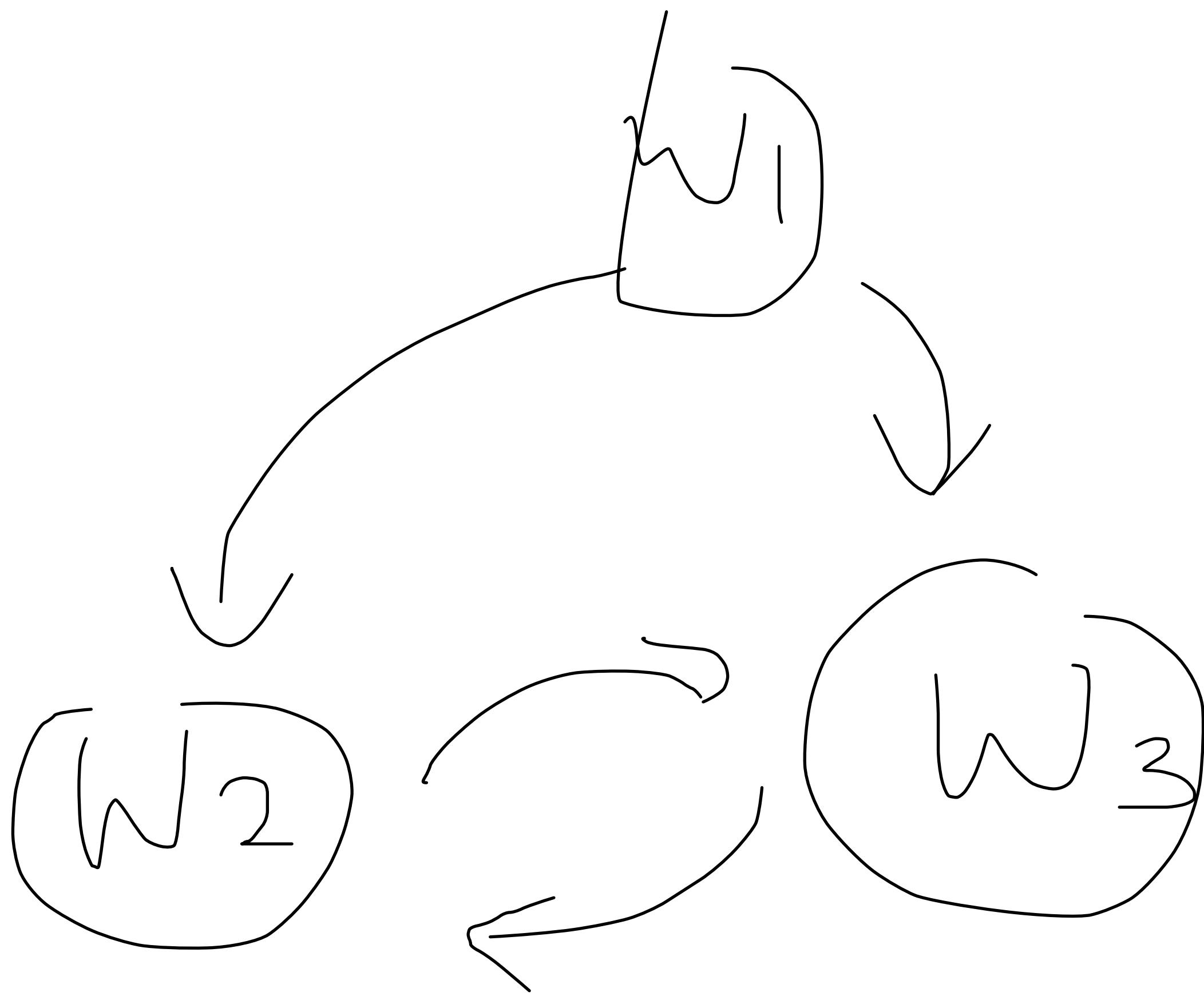
$$\sum_{k=1}^m V_k = 0$$

We will do all this using  
matrices

## 2) Google's PageRank Given

web pages  $w_1, w_2, \dots, w_n$ ,  
construct an  $n$  by  $n$  square  
matrix with all nonnegative  
entries,  $(i,j)$  entry is  
equal to one if there is  
a link from  $w_j$  to  $w_i$ ,  
zero if there is no link

Picture



Matrix  $1 \times 3 \times 3$

$$\begin{pmatrix} 0 & 0 & 0 \\ 1 & 0 & 1 \\ 1 & 1 & 0 \end{pmatrix}$$

Perron - Frobenius Theory

gives you a vector

$v = (v_1, \dots, v_n)$  such

that each  $v_i$  is nonnegative  
and represents the probability  
that a "random surfer" will  
arrive at the page  $w_i$ .

This is Google's PageRank  
algorithm in essence

### 3) Fast Fourier Transform

Given a signal (radio, phone, etc) that is **band-limited**  
- frequency components are bounded.

We can think of the signal  
as a continuous function  $f$  on  
 $(-\infty, \infty)$ . Suppose  $\int_{-\infty}^{\infty} |f(x)| dx$   
is finite

Nyquist's lemma gives us that  
 $f$  is determined by its values  
at finitely many points.

We then reconstruct  $f$

via the discrete Fourier transform.

With 2 points, the  
discrete Fourier transform  
is the matrix

$$\begin{pmatrix} 1 & -1 \\ -1 & 1 \end{pmatrix}$$

(sometimes scaled by  $\frac{1}{\sqrt{2}}$ )

For n points, the Fourier  
transform is an n by n matrix,

## 4) Compressed Sensing

Given a system of linear equations with more unknowns than equations,

if there is a unique "sparse" (= many zero entries)

solution, then the solution may be recovered

Image recognition, resolution

$$(I_0 \rightarrow h_1)$$

Fourier transform  $\hat{g}(\zeta)$   
comes into play.

## 5) Special Relativity

Space-time position  
given by a 4-vector

$$v = (v_1, v_2, v_3, v_4)$$

Minkowski length of  $v$

$$\sqrt{-v_1^2 + v_2^2 + v_3^2 + v_4^2}$$

Lorentz transformations  
are (some) of the length  
preserving transformations  
These are matrices

## 6) Quantum Mechanics

Measurement and time-evolution  
operations are given by matrices -  
but they may have infinitely  
many entries!